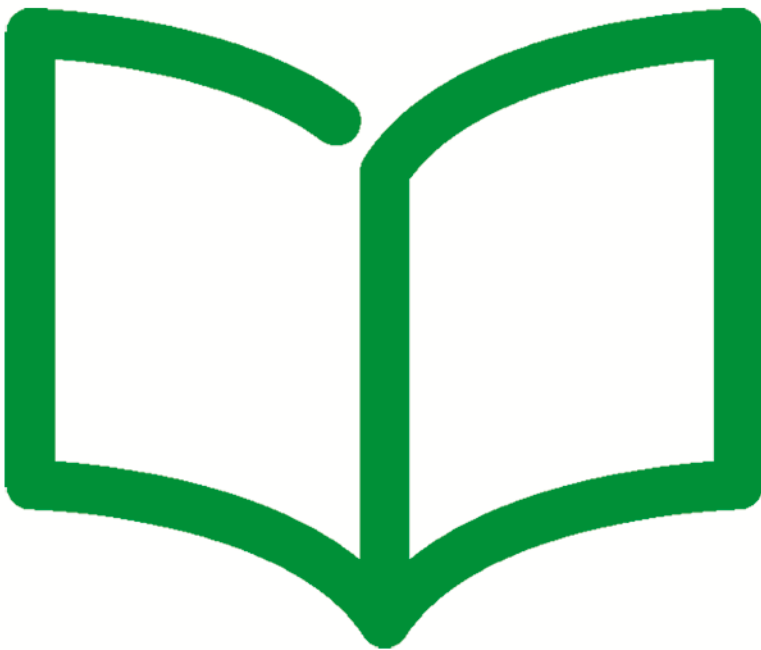


# Data Sheet

## PacDrive™ C600 Controller

ETIE 099 / 2009-05-05  
Article Nr.: 17130203-001



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# 1 Overview

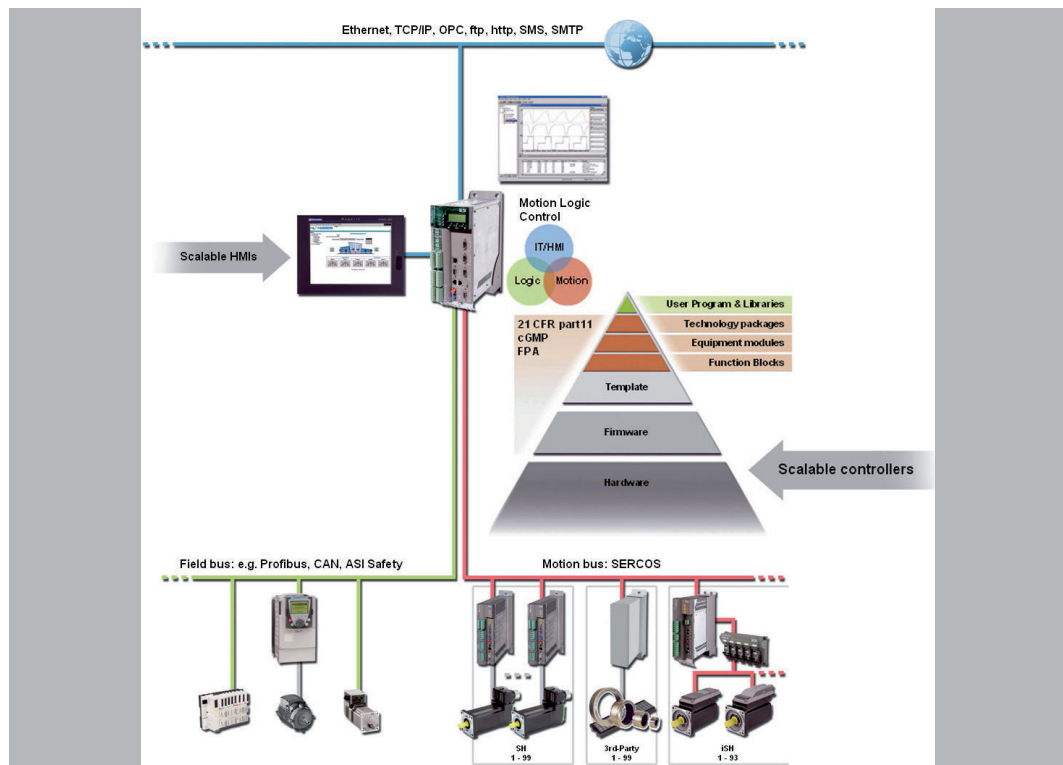


Figure 1-1: PacDrive System Overview

## C600 Controller

### Controller based architecture

The PacDrive C600 Controller is based on an Intel module processor. It uses the real-time operating system VxWorks. VxWorks provides logic and motion functions for a production or packaging machine. A PacDrive Controller synchronizes, coordinates and generates the positioning functions for up to 99 servo drives, which are connected via the SERCOS bus interface.

Several standardized field bus interfaces are available: PROFIBUS DP, CAN, CANopen or DeviceNet. A variety of standard HMI systems, ranging from low-cost text displays to industrial PCs, can be used for the HMI functions.

- CPU: Intel Module, 1.6 GHz, 256 MB RAM
- Real-Time operating system: VxWorks
- IEC 61131-3 programming languages for PLC and Motion Control
- SERCOS interface
- Profibus DP, CAN, CANopen, DeviceNet, or Ethernet/IP
- Digital inputs, digital outputs, analog, interrupt and Touchprobe inputs
- Communication interfaces: RS 232, RS 485, Ethernet (TCP/IP)
- CompactFlash™ card (≥128 MB)
- Includes OPC server for Windows-based HMIs
- Teleservice via web server or modem

## 2 Technical data

### 2.1 Ambient conditions

Procedure	Parameters	Value	Basis
Operation	<b>Class 3K3</b>		IEC/EN 60721-3-3
	Ambient temperature	+5°C...+45°C	
	Condensation	Prohibited	
	Icing	Prohibited	
	Another water	Prohibited	
	Relative humidity	5% ... 85%	
Transport	<b>Class 2K3</b>		IEC/EN 60721-3-2
	Ambient temperature	-25°C...+70°C	
	Condensation	Prohibited	
	Icing	Prohibited	
	Another water	Prohibited	
	Relative humidity	5% ... 95%	
Long time storage in transport packaging	<b>Class 1K4</b>		IEC/EN 60721-3-1
	Ambient temperature	-25°C...+55°C	
	Condensation	Prohibited	
	Icing	Prohibited	
	Another water	Prohibited	
	Relative humidity	5% ... 95%	

Table 2-1: Ambient conditions PacDrive C600 Controller

Procedure	Parameters	Value	Basis
Operation	<b>Class 3K3</b>		IEC/EN 60721-3-3
	Ambient temperature	+5°C...+40°C	
	Condensation	Prohibited	
	Icing	Prohibited	
	Another water	Prohibited	
	Relative humidity	5% ... 85%	
Transport	<b>Class 2K3</b>		IEC/EN 60721-3-2
	Ambient temperature	-25°C...+50°C	
	Condensation	Prohibited	
	Icing	Prohibited	
	Another water	Prohibited	
	Relative humidity	5% ... 95%	
Long time storage in transport packaging	<b>Class 1K3</b>		IEC/EN 60721-3-1
	Ambient temperature	-5°C...+45°C	
	Condensation	Prohibited	
	Icing	Prohibited	
	Another water	Prohibited	
	Relative humidity	5% ... 95%	

Table 2-2: Ambient conditions PacDrive C600 Controller (with UPS)

## 2.2 Standards and regulations

Certifications	CE, UL , cUL
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Table 2-3: Standards and regulations PacDrive C600 Controller

## 2.3 Mechanical and electrical data

Category	Parameters	Value
<b>Product configuration</b>	Type key C600 up to 99 SERCOS slaves (SERCOS slaves = MC-4, SCL, iSH)	PacDrive C600 / 10 / 1 / 1 / 1 / 00
	Order number- C600 up to 99 SERCOS slaves	13 13 02 62
<b>Processor</b>	CPU	Intel Pentium M 1.6 GHz
	RAM	256 MB
	L2 Cache	1 MB
	NVRAM	256 kB
	CompactFlash™ card	≥128 MB
	Real time clock (RTC)	Yes (battery maintenance interval: 5 years)
	Watchdog	Yes (max. 60 V < 2 A)
	Diagnosis	Alphanumeric diagnosis display Status LEDs
<b>Operating system</b>	Real-time operating system	VxWorks
<b>Programming languages</b>	Programming languages IEC 61131-3	Instruction list (IL)
		Ladder diagram (LD)
		Function block diagram (FBD)
		Sequential function chart (SFC)
		Structured text (ST)
		Continuous function chart (CFC)

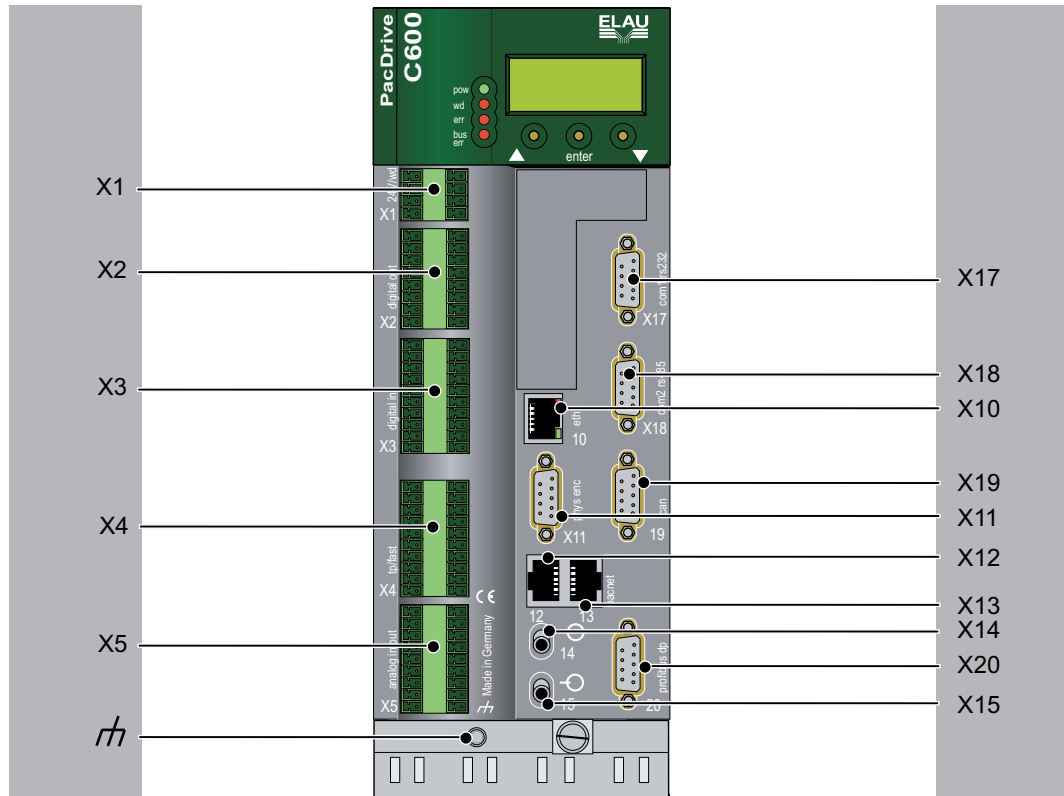
Category	Parameters	Value
<b>Interfaces</b>	Serial interfaces	COM1: RS232 (X17)
		COM2: RS485 (X18)
	Network connection	Ethernet (10/100 Base-T) (X10)
	Field bus connection	PROFIBUS DP Master/Slave (12 MBaud) (X20) and CAN (2.0A) or CANopen (X19)
		DeviceNet Slave (cable adapter required)
		EtherNet/IP Slave (optional hardware module required)
		EtherNet/IP Scanner (optional hardware module required)
	Real-time bus interface	SERCOS interface (16 MBaud) (X14, X15)
	PacNet interface	2 PacNet interfaces (X12, X13)
	Master encoder interface	1 SinCos master encoder or
		1 incremental master encoder (X11)
	HMI interface	RS485 (Modbus or PROFIBUS DP)
		HMI software tools: OPC server (for Windows NT/2000/XP or Windows CE)
	Diagnostic interface for remote maintenance	Modem
	Communications protocols	Http
Ftp		
SMTP (E-Mail)		
Integrated trace recorder (soft- ware oscilloscope)	8 channels, resolution 1 ms	
Integrated data logger for diag- nostic messages	27 kB	
<b>Output</b>	Actuator power	99 servo axes with all SERCOS cycle times
		Max. of 255 parallel motion profiles possible
<b>SPS output</b>	Time for 1000 Bit instructions	4 $\mu$ s
	Number of PLC processes	Unlimited
	Type of PLC processes	Continuous
		periodic or
		Event-controlled
	Cycle time fast task	250 $\mu$ s
Nominal I/O response time	500 $\mu$ s (read in data, process, set output)	
<b>Cam Switch Group</b>	Number of cams	Max. 256
	Sequential circuit	Dynamic
	Outputs	Memory or digital outputs
	Inputs	External master encoder
		Virtual master encoder
		Axis position
Processing time	250 $\mu$ s	
<b>Digital inputs (X3)</b>	Number	20 (IEC61131-2 type 1)
	Range $U_{IN}$ 0 Voltage	DC 0 ... 6 V
	Range $U_{IN}$ 1 Voltage	DC 20 ... 33 V
	Input data	$I_{IN} = 5$ mA by $U_{IN} = 24$ V
	Polarized	Yes
	Input filter	1 or 5 ms can be parameterized

Category	Parameters	Value
<b>Analog inputs (X5)</b>	Number	2
	Range $U_{IN}$	-10 ... 10 V
	Resolution	12 Bit (5 mV, resistor 100 kOhm)
	Range $I_{IN}$	-20 ... 20 mA
	Resolution	12 Bit (5 $\mu$ A, resistor 500 Ohm)
<b>Interrupt inputs (X4)</b>	Number	4 (IEC61131-2 type 1)
	Range $U_{IN}$ 0 Voltage	DC 0 ... 6 V
	Range $U_{IN}$ 1 Voltage	DC 20 ... 33 V
	Input data	$I_{IN} = 5$ mA by $U_{IN} = 24$ V
	Polarized	Yes
	Input filter	0.1 or 1 ms can be parameterized
<b>Touchprobe inputs (X4)</b>	Number:	16 (IEC61131-2 type 1)
	Range $U_{IN}$ 0 Voltage	DC 0 ... 6 V
	Range $U_{IN}$ 1 Voltage	DC 20 ... 33 V
	Input data	$I_{IN} = 5$ mA by $U_{IN} = 24$ V
	Polarized	Yes
	Input filter TP0 to TP15	100 $\mu$ s resolution 10 $\mu$ s at a cycle time of 1, 2, 4 ms
<b>Digital outputs (X2)</b>	Number	16 (IEC61131-2 type 1)
	Output voltage	(+UL-3 V) < $U_{OUT}$ < +UL
	Rated current	$I_e = 250$ mA per output
	Inrush current	$I_{emax} < 2$ A for 1 s
	Leakage current with 0 signal	< 0.4 mA
	Transmission time	100 $\mu$ s
	short circuit proof	Yes
	Supply output	DC 24 V (-15% / +25%) / 3 A
<b>Analog outputs (X5)</b>	Number	2
	Range $U_{OUT}$	-10 ... 10 V
	Resolution	12 Bit (5 mV)
	Load	> 5 kOhm (max. Offset < +/-75 mV)
<b>Additional digital and analog I/Os</b>	Via field bus	Max. 3,584 bytes digital/analog inputs and Max. 3,584 bytes digital/analog outputs Max. number of stations: 126 (PROFIBUS)
	Additional fast digital I/Os	Via PacNet Max. 128 inputs and 128 outputs
	Additional Touchprobe inputs	Via PacNet Max. 128 Touchprobe inputs
<b>Power supply</b>	Power supply unit	DC 24 V (-15% / +25%) / max. 3.0 A without UPS and 4.5 A with UPS
	Power consumption	Max. 85 W
	Uninterruptible Power Supply (UPS)	Internal, optional (maintenance interval 3 years)
<b>Dimensions</b>	Dimensions packaging	DxWxH (mm): 300x130x400
<b>Weight</b>	Weight (with packaging)	3.5 kg (4.1 kg)
<b>Protection class</b>	Housing	IP 20

Category	Parameters	Value
Isolation class	Degree of pollution	2

Table 2-4: Technical data PacDrive C600 Controller

## 2.4 Electrical connections

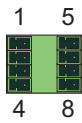


Connection	Meaning	max. terminal cross-section [mm <sup>2</sup> ]/ [AWG]	
X1	Control voltage/ Watchdog	1.50 mm <sup>2</sup>	28 - 16
X2	Digital outputs	1.50 mm <sup>2</sup>	28 - 16
X3	Digital inputs	1.50 mm <sup>2</sup>	28 - 16
X4	Touchprobe and fast digital inputs	1.50 mm <sup>2</sup>	28 - 16
X5	Analog inputs/outputs	1.50 mm <sup>2</sup>	28 - 16
X10	Ethernet connection	-	-
X11	Master encoder (SinCos)	0.25 mm <sup>2</sup>	-
X11	Master encoder (incremental)	0.25 mm <sup>2</sup>	-
X12/X13	PacNet	-	-
X17	Com 1 (RS232)	0.25 mm <sup>2</sup>	-
X18	Com 2 (RS485)	0.25 mm <sup>2</sup>	-
X19	CAN	0.25 mm <sup>2</sup>	-
X20	PROFIBUS db	0.25 mm <sup>2</sup>	-
⌚	Shielded connector	-	-

Table 2-5: Connection overview PacDrive C600 Controller



### X1 - Control voltage and watchdog



Pin	Designation	Meaning	Range
1	DC +24 V	Supply voltage	- 15 % / +25 %
2	DC 0 V	Supply voltage	
3	+UL	For digital outputs	DC +24 V -15 % / +25 %
4	L0	For digital inputs/outputs	
5	DC +24 V	Supply voltage (with pin 1 bridged, max. ampacity 4A)	-15 % / +25 %
6	DC 0 V	Supply voltage (with pin 2 bridged, max. ampacity 4A)	
7	WD	Watchdog relay	
8	WD	Watchdog relay	

Table 2-6: Connection X1

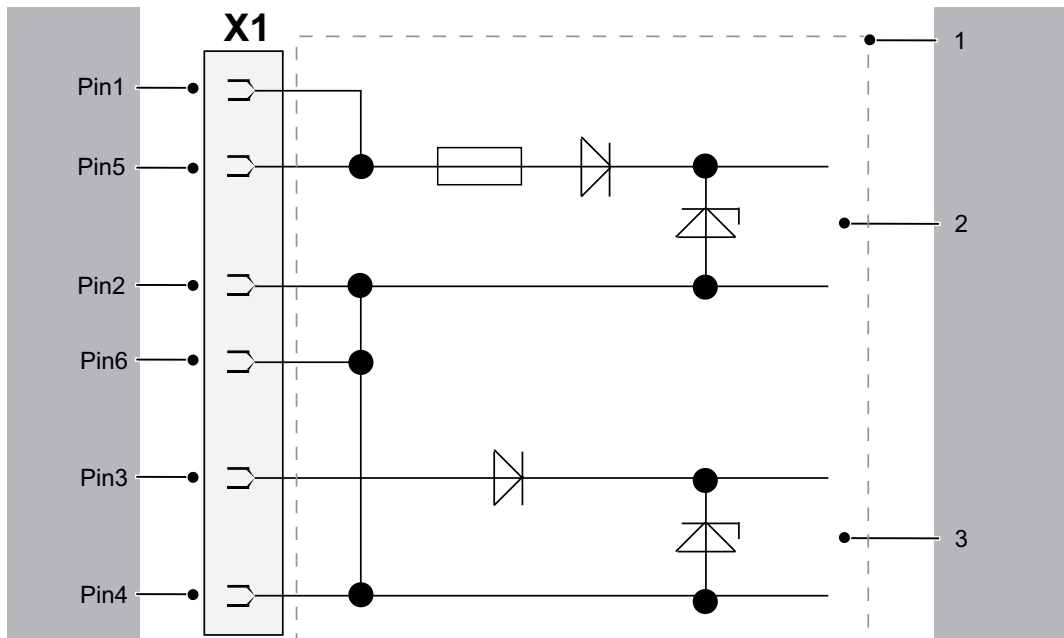
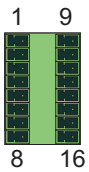


Figure 2-1: Connection X1 - Input connection

1	Internal wiring diagram - input connection of power supply (simplified)
2	Internal supply voltage
3	Supply voltage for digital outputs/inputs

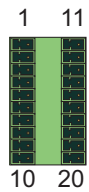
## X2 - Digital outputs



Pin	Designation	Meaning	Range
1	O.00	Digital output 1	DC 20 ... 30 V
2	O.01	Digital output 2	DC 20 ... 30 V
3	O.02	Digital output 3	DC 20 ... 30 V
4	O.03	Digital output 4	DC 20 ... 30 V
5	O.04	Digital output 5	DC 20 ... 30 V
6	O.05	Digital output 6	DC 20 ... 30 V
7	O.06	Digital output 7	DC 20 ... 30 V
8	O.07	Digital output 8	DC 20 ... 30 V
9	O.08	Digital output 9	DC 20 ... 30 V
10	O.09	Digital output 10	DC 20 ... 30 V
11	O.10	Digital output 11	DC 20 ... 30 V
12	O.11	Digital output 12	DC 20 ... 30 V
13	O.12	Digital output 13	DC 20 ... 30 V
14	O.13	Digital output 14	DC 20 ... 30 V
15	O.14	Digital output 15	DC 20 ... 30 V
16	O.15	Digital output 16	DC 20 ... 30 V

Table 2-7: Connection X2

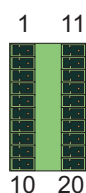
## X3 - Digital inputs



Pin	Designation	Meaning	Range
1	I.00	Digital input 0	DC 20 ... 30 V
2	I.01	Digital input 1	DC 20 ... 30 V
3	I.02	Digital input 2	DC 20 ... 30 V
4	I.03	Digital input 3	DC 20 ... 30 V
5	I.04	Digital input 4	DC 20 ... 30 V
6	I.05	Digital input 5	DC 20 ... 30 V
7	I.06	Digital input 6	DC 20 ... 30 V
8	I.07	Digital input 7	DC 20 ... 30 V
9	I.08	Digital input 8	DC 20 ... 30 V
10	I.09	Digital input 9	DC 20 ... 30 V
11	I.10	Digital input 10	DC 20 ... 30 V
12	I.11	Digital input 11	DC 20 ... 30 V
13	I.12	Digital input 12	DC 20 ... 30 V
14	I.13	Digital input 13	DC 20 ... 30 V
15	I.14	Digital input 14	DC 20 ... 30 V
16	I.15	Digital input 15	DC 20 ... 30 V
17	I.16	Digital input 16	DC 20 ... 30 V
18	I.17	Digital input 17	DC 20 ... 30 V
19	I.18	Digital input 18	DC 20 ... 30 V
20	I.19	Digital input 19	DC 20 ... 30 V

Table 2-8: Connection X3

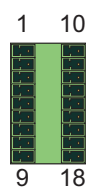
## X4 - Touchprobe and fast digital inputs



Pin	Designation	Meaning	Range
1	T.00	Touchprobe input 0	DC 20 ... 30 V
2	T.01	Touchprobe input 1	DC 20 ... 30 V
3	T.02	Touchprobe input 2	DC 20 ... 30 V
4	T.03	Touchprobe input 3	DC 20 ... 30 V
5	T.04	Touchprobe input 4	DC 20 ... 30 V
6	T.05	Touchprobe input 5	DC 20 ... 30 V
7	T.06	Touchprobe input 6	DC 20 ... 30 V
8	T.07	Touchprobe input 7	DC 20 ... 30 V
9	T.08	Touchprobe input 8	DC 20 ... 30 V
10	T.09	Touchprobe input 9	DC 20 ... 30 V
11	T.10	Touchprobe input 10	DC 20 ... 30 V
12	T.11	Touchprobe input 11	DC 20 ... 30 V
13	T.12	Touchprobe input 12	DC 20 ... 30 V
14	T.13	Touchprobe input 13	DC 20 ... 30 V
15	T.14	Touchprobe input 14	DC 20 ... 30 V
16	T.15	Touchprobe input 15	DC 20 ... 30 V
17	F.00	Fast input 1	DC 20 ... 30 V
18	F.01	Fast input 2	DC 20 ... 30 V
19	F.02	Fast input 3	DC 20 ... 30 V
20	F.03	Fast input 4	DC 20 ... 30 V

Table 2-9: Connection X4

## X5 - Analog inputs/outputs



Pin	Designation	Meaning	Range
1	AI.0 +	Analog input 0+	-10 ... +10 V <sup>(*)</sup> 0 ... 20 mA <sup>(**)</sup>
2	J.0 +	Br. current input 0 +	
3	AI.0 -	Analog input 0-	
4	A.GND 0	Analog ground 0	
5	12 V Out 0	Output voltage 0	12 V
6	PE	Shield	
7	AO.0	Analog output 0	-10 ... +10 V
8	A.GND AO.0	Analog ground 0	
9	PE	Shield	
10	AI.1 +	Analog input 1+	-10 ... +10 V <sup>(*)</sup> 0 ... 20 mA <sup>(**)</sup>
11	J.1 +	Br. current input 1 +	
12	AI.1 -	Analog input 1-	
13	A.GND 1	Analog ground	
14	12 V Out 1	Output voltage 1	12 V
15	PE	Shield	
16	AO.1	Analog output 1	-10 ... +10 V
17	A.GND AO.1	Analog ground	
18	PE	Shield	

<sup>(\*)</sup> Voltage metering and <sup>(\*\*)</sup>current measurement on AI.0+ / AI.0- (Pin 1 / Pin 3) and AI.1+ / AI.1- (Pin 10 / Pin 12)  
<sup>(\*\*)</sup>Current measurement by bridging to J.0+ (Pin 2) or. J.1+ (Pin 11).

Table 2-10: Connection X5

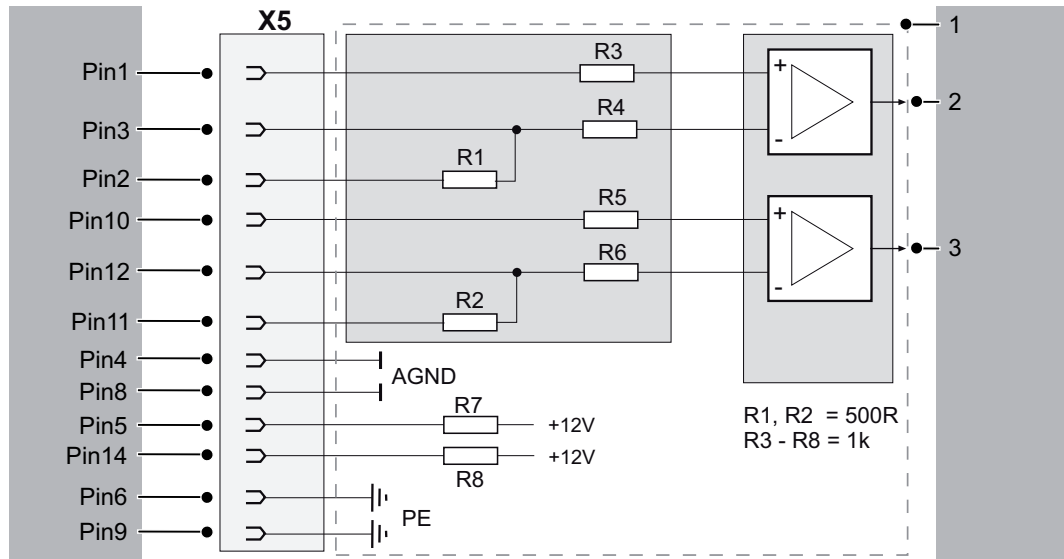
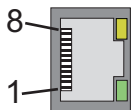


Figure 2-2: Connection X5 - Input connection

1	Internal wiring diagram - input connections for analog inputs (simplified)
2	Analog Input 1
3	Analog Input 2

**X10 - Ethernet**



Pin	Designation	Meaning	Range
1	Tx+	OutputTransmitData+	
2	Tx-	OutputTransmitData-	
3	Rx+	InputReceiveData+	
4	-	(PE)	
5	-	(PE)	
6	Rx-	InputReceiveData-	
7	-	(PE)	
8	-	(PE)	

Table 2-11: Connection X10

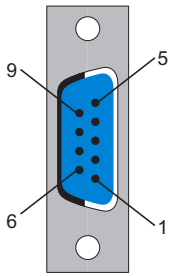


Depending on the application, you will need different cables to connect the controller via the RJ-45 outlet.

Component A	Component B	required cable
PacDrive Controller	"Firm network" with RJ-45	Commercially available patch cable
PacDrive Controller	Hub	Commercially available patch cable
PacDrive Controller	PC	Crossed RJ-45 network cable

- ▶ In case of doubt, ask your network administrator.

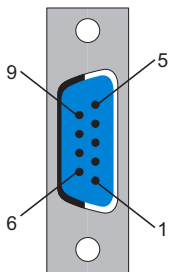
### X11 - Master encoder (SinCos)



Pin	Designation	Meaning	Range
1	REFSIN	Reference Signal Sinus	
2	SIN	Sinus trace	
3	REFCOS	Reference Signal Cosinus	
4	COS	Cosinus trace	
5	+9 V	Supply voltage	
6	RS485-	Parameter channel -	
7	RS485+	Parameter channel +	
8	SC_SEL	Master encoder plugged in (bridge to GND)	
9	GND	Supply voltage	

Table 2-12: Connection X11 - Master encoder (SinCos)

### X11 - Master encoder (incremental)



Pin	Designation	Meaning	Range
1	_UA	Track A	
2	UA	Track A	
3	_UB	Track B	
4	UB	Track B	
5	+5 V	Supply voltage	
6	_UO	Track O	
7	UO	Track O	
8	-	-	
9	GND	Ground	

Table 2-13: Connection X11 - Master encoder (incremental)

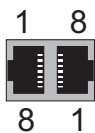
## ⚠ CAUTION

### PLUGGING IN/UNPLUGGING THE MASTER ENCODER PLUG WHEN SWITCHED ON

- Only unplug or plug in master encoder when off-circuit.
- Disconnect controller from the 24 V supply voltage.

Failure to follow these instructions can result in equipment damage.

### X12/13 - PacNet



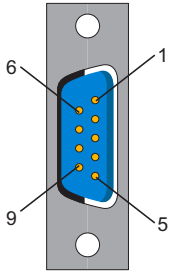
Pin	Designation	Meaning	Range
1	TxD+	OutputTransmitData+	
2	TxD-	OutputTransmitData-	
3	RxD+	InputReceiveData+	
4	TxC-	OutputTransmitClock-	
5	TXC+	OutputTransmitClock+	
6	RxD-	InputReceiveData-	
7	RxC+	InputReceiveClock+	
8	RxC-	InputReceiveClock-	

Table 2-14: Connection X12, X13



Use only approved PacNet cables at the PacNet connection to avoid malfunction.

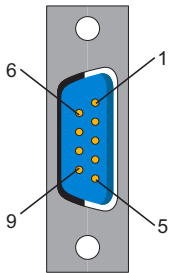
**X17 - Com 1 (RS 232)**



Pin	Designation	Meaning	Range
1	DCD	Data Carrier Detect	
2	RxD	Receive Data	
3	TxD	Transmit Data	
4	DTR	Data Terminal Ready	
5	GND	Signal Ground	
6	DSR	Data Set Ready Clear To Send	
7	RTS	Request To Send	
8	CTS	Clear To Send	
9	RI	Ring Indicator	

Table 2-15: Connection X17

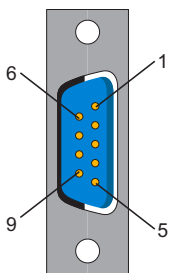
**X18 - Com 2 (RS485)**



Pin	Designation	Meaning	Range
1	+5 VM	Supply voltage	
2	TxD-	RS485 Transmit -	
3	TxD+	RS485 Transmit+	
4	RxD+	RS485 Receive +	
5	RxD-	RS485 Receive -	
6	GNDR	GND receive RS485	
7	-	Reserved	
8	GNDM	Supply voltage	
9	GNDR	GND receive RS485	

Table 2-16: Connection X18

**X19 - CAN**



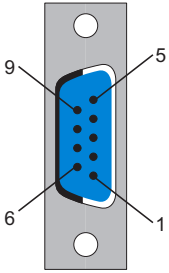
Pin	Designation	Meaning	Range
1	-	Reserved	
2	CAN_L	Bus line (low)	
3	GND	Ground	
4	-	Reserved	
5	-	Reserved	
6	-	Reserved	
7	CAN_H	Bus line (high)	
8	-	Reserved	
9	-	Reserved	

Table 2-17: Connection X19



An adapter is available for the connection to DeviceNet.

**X20 - profibus db**



Pin	Designation	Meaning	Range
1	PE	Shield	
2	-	Reserved	
3	RxD / TxD -P	Data -P	
4	CNTR-P	Control signal P	
5	DGND	Signal ground	
6	VP	Supply voltage	
7	-	Reserved	
8	RxD / TxD -N	Data -N	
9		Reserved	

Table 2-18: Connection X20

**Connector**

A PROFIBUS connector must be used to connect to the 9 pole PROFIBUS outlet because the bus terminal resistors are in this connector. The possible PROFIBUS connectors with different cable outlets are illustrated below.

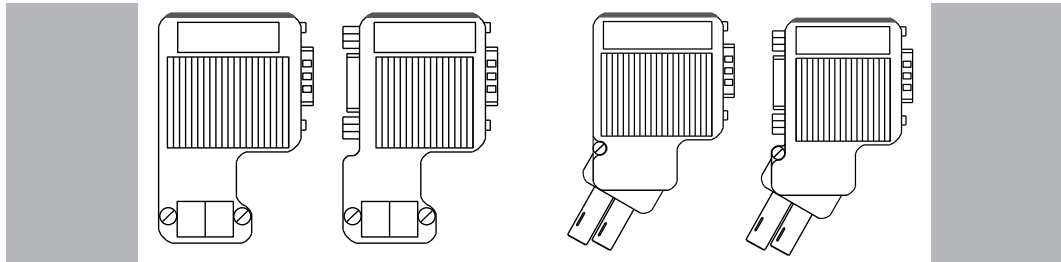


Figure 2-3: PROFIBUS connector

**Bus terminal resistors**

For the first and last bus nodes, the terminal resistors must be switched on. Otherwise data transmission will not function properly. The shielding must be applied generously and on both sides.

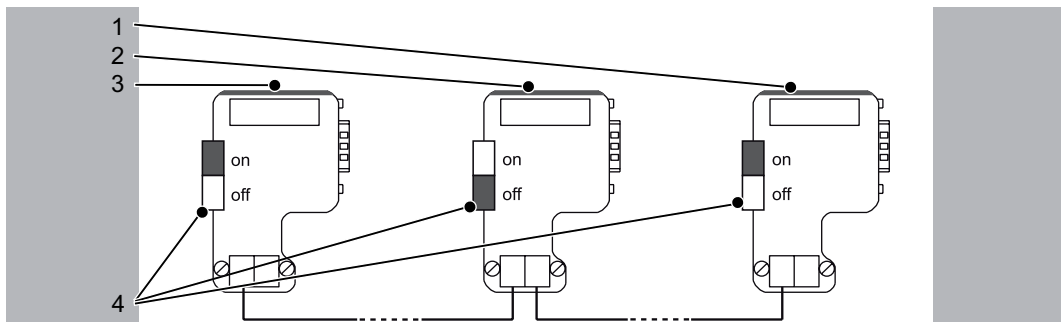


Figure 2-4: Position of the bus terminal resistors

1	Last bus slave
2	Nth bus slave
3	First bus slave
4	Bus terminator

## 2.5 Dimensions

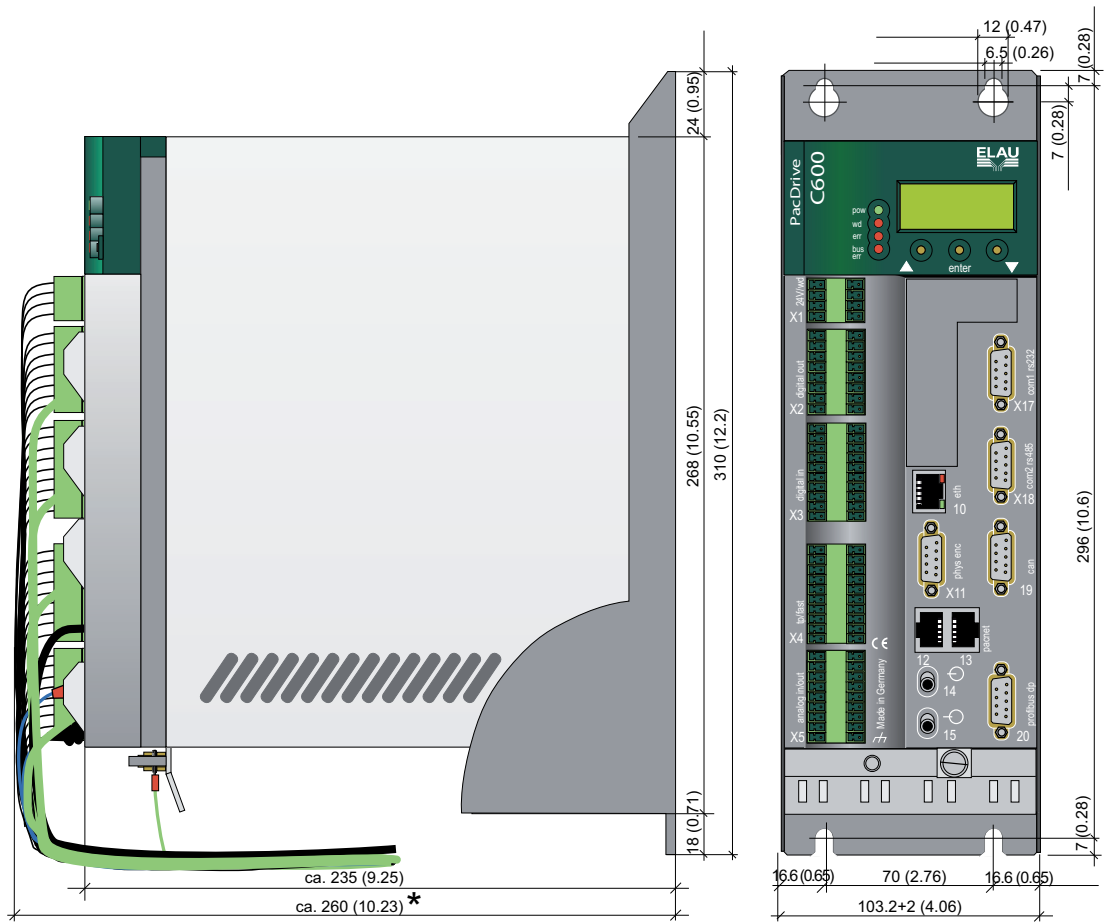


Figure 2-5: Dimensions PacDrive C600 Controller



### 3 Type code

**Product ID Code**

**C600 / 10 / 1 / 1 / 1 / 00**

**HW-Variant**

**Processor**

1 = Intel Pentium M 1.6 GHz

**RAM**

1 = 256 MB

**Flash memory**

1 = 32 MB

**Optionelle Funktionen**

